

ADM-Aeolus wind retrievals for NWP

DGH Tan
ECMWF

Acknowledgments:

ESA (Mission Experts Division & Aeolus project team)

Aeolus Mission Advisory Group

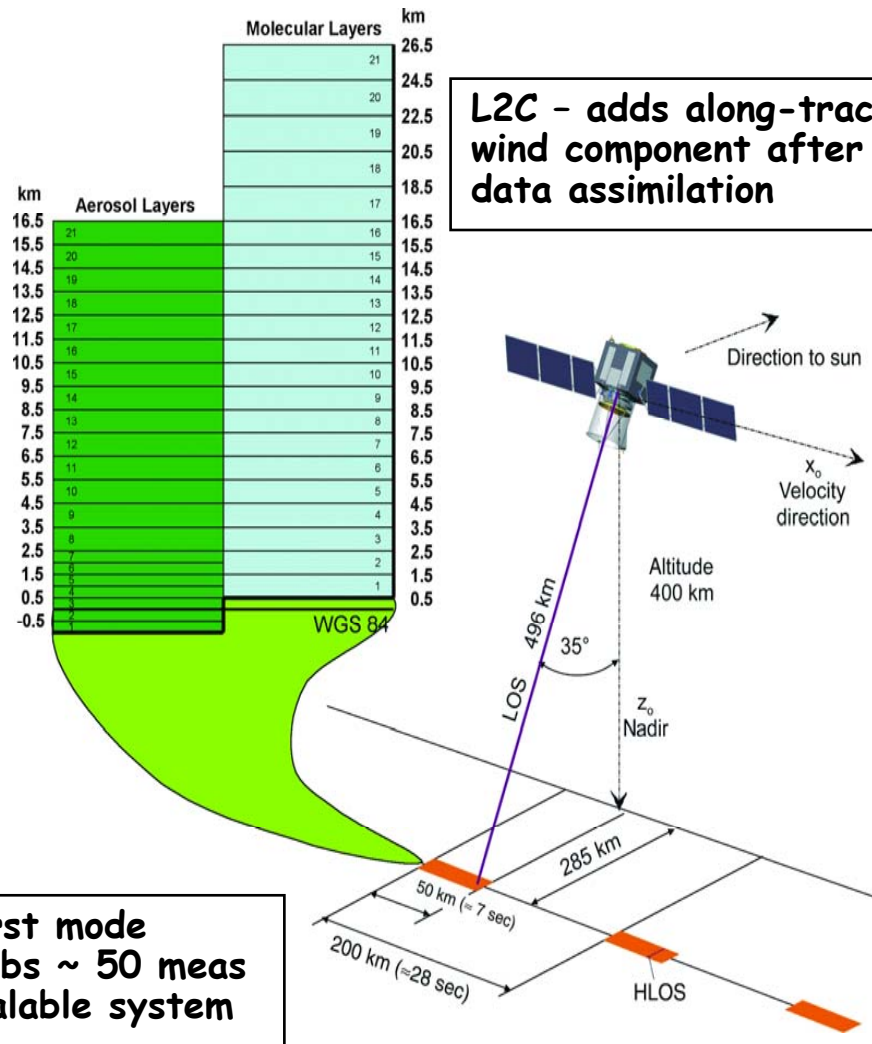
Level-1B/2A/2B Development Teams

Overview - almost ready for launch

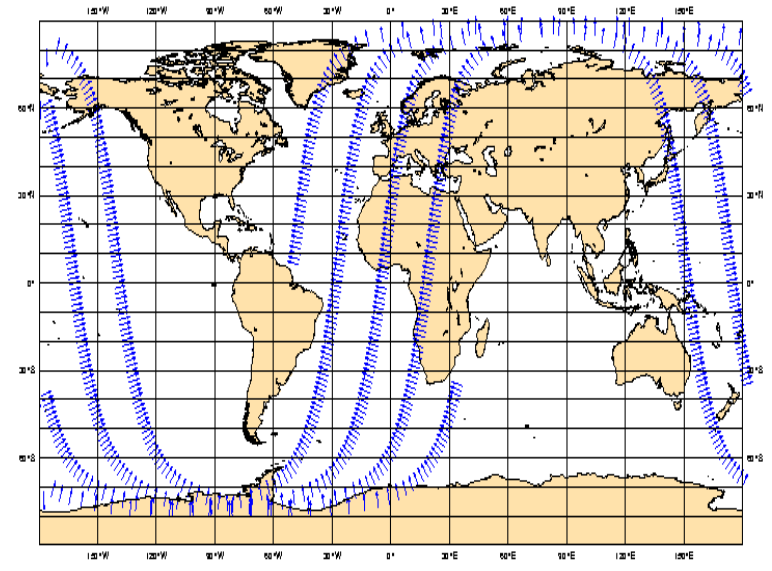
- ◆ **ECMWF preparations 2002-2004**
 - ◆ Example for other NWP centres
- ◆ **Level-2B processor development**
 - ◆ ECMWF is lead institute, 5 sub-contractors
 - ◆ 2004-present
- ◆ **Other ongoing work/operational phase**
 - ◆ GSOV, Cal/Val, In-orbit commissioning
 - ◆ ECMWF to generate operational L2B/L2C products, monitor & assimilate Aeolus data, assess impact on NWP
 - ◆ Maintain, develop & distribute L2B processor
 - On behalf of ESA, using NWP-SAF approach

Product for assimilation - L2B 50km hlos wind

ADM-Aeolus Baseline



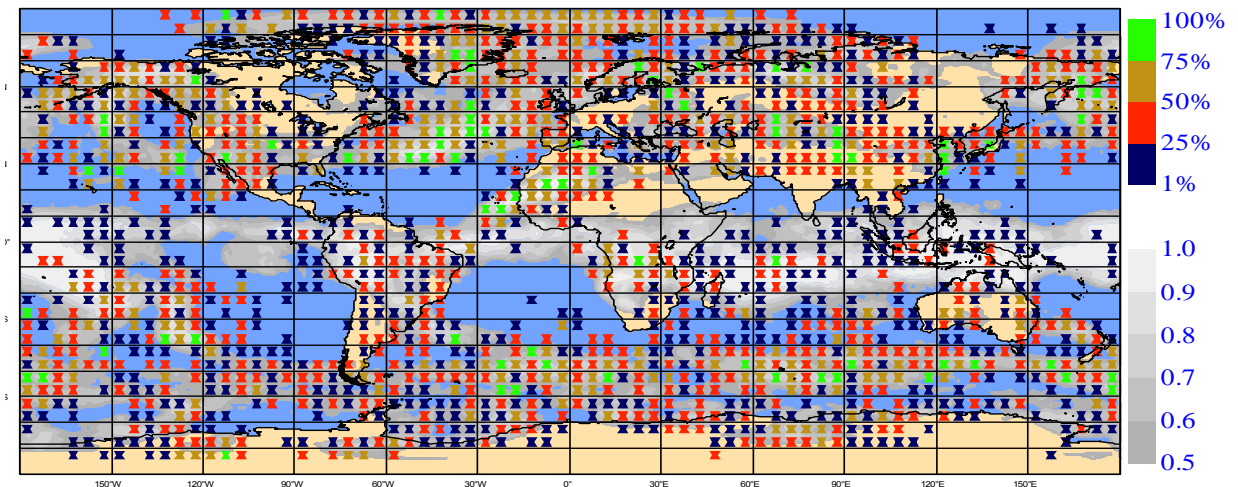
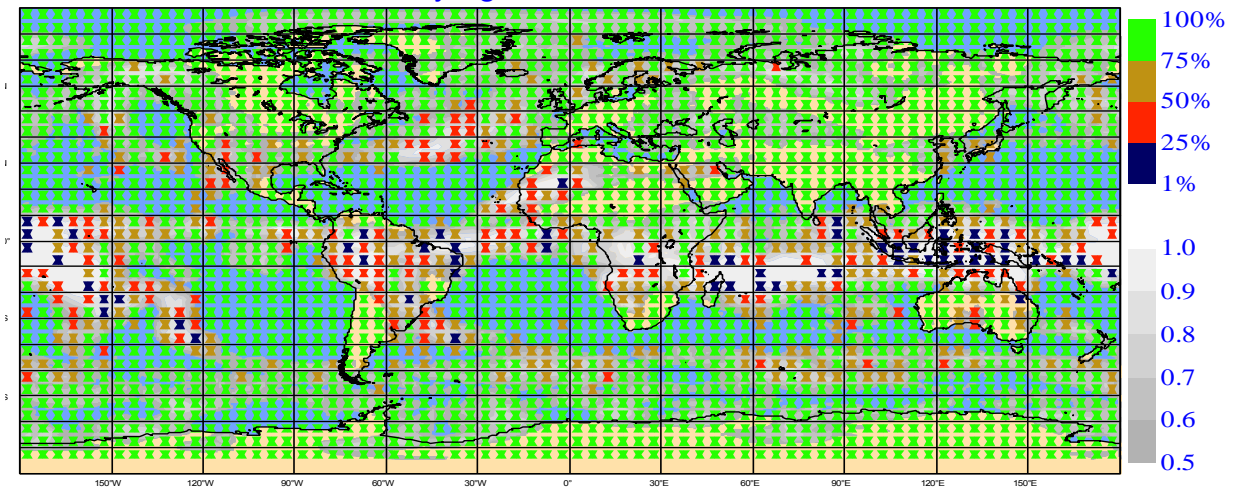
- UV lidar (355 nm) with **two** receivers
- Mie (aerosol), Rayleigh (molecules)
 - both use direct detection
- Wind profiles from surface to 30 km with resolution varying from 0.5 to 2 km
- vertical bins configurable in flight
 - HLOS component only
 - direction 7° from zonal at equator
 - 6 hour coverage shown



L2B data simulated using ECMWF clouds ...

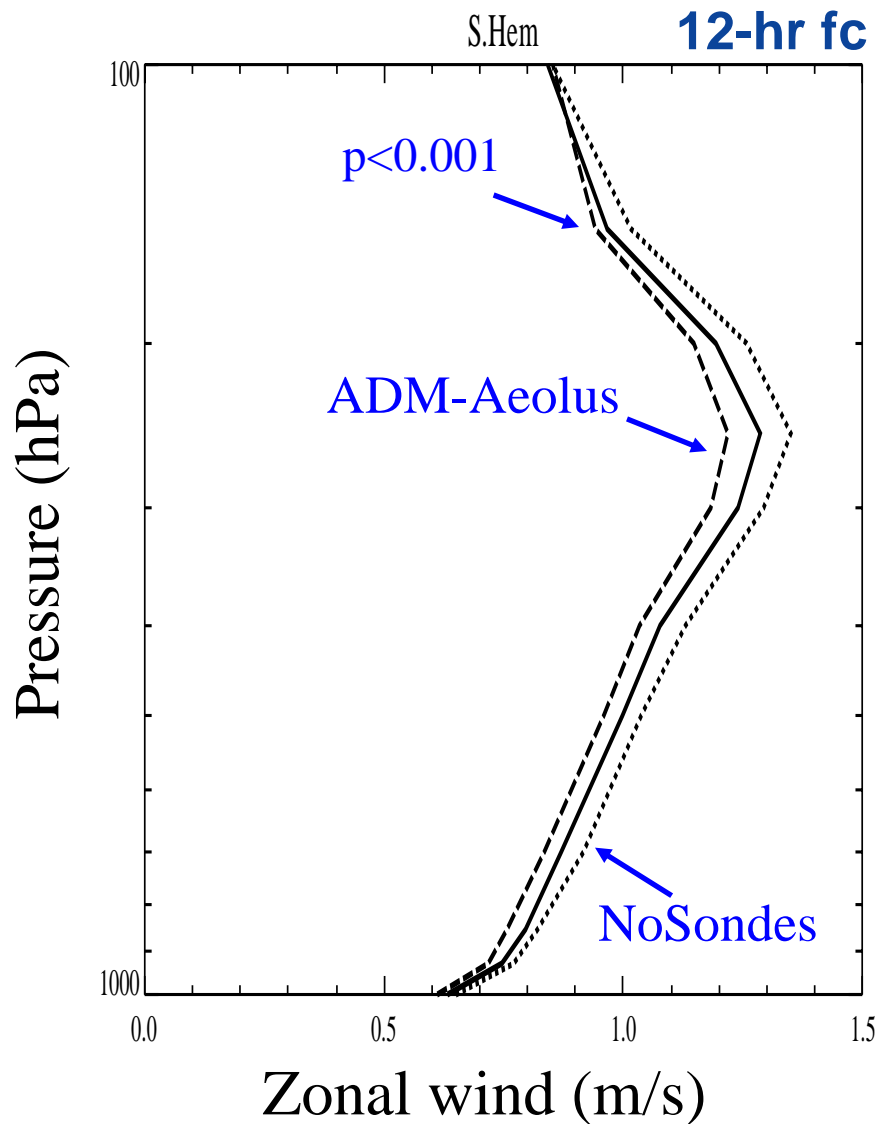
- ◆ 90% of Rayleigh data have accuracy better than 2 m/s
- ◆ In priority areas (filling data gaps in tropics & over oceans)
- ◆ Complemented by good Mie data from cloud-tops/cirrus (5 to 10%)
- ◆ Tan & Andersson QJRMS 2005

Yield (data meeting mission requirements in % terms) at 10 km



LIPAS-simulated HLOS data - operational processors later

... & impact studied via assimilation ensembles



Spread in zonal wind (U , m/s)

Scaling factor ~ 2 for wind error

Tropics, N. & S. Hem all similar

Simulated DWL adds value at all altitudes and in longer-range forecasts (T+48, T+120)

Differences significant (T-test)

Supported by information content diagnostics

Cheaper than OSSEs

Global information content - consistent

◆ Mike Fisher for Entropy Reduction & DFS

$S \sim \log(\det(P^A))$
 $\sim \text{tr} (\log (J''^{-1}))$
 $J'' = 4d\text{-var Hessian}$
 $P^A = \text{analysis error covar.}$

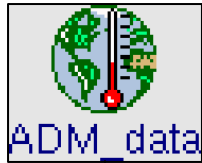
◆ DWL data are accurate and fill data gaps

◆ subject to usual caveats about simulated data

	TEMP/PILOT	Simulated DWL
Data considered	u,v to 55 hPa	HLOS
Entropy_Reduction (“Info bits”)	4830	3123
Deg_Free_Sig	3707	2743
N_Obs	90688	50278
Info bits per obs	0.053	0.062
N_Obs/Deg_Free_Sig	24.5	18.3
Redundancy		2 — 3 %

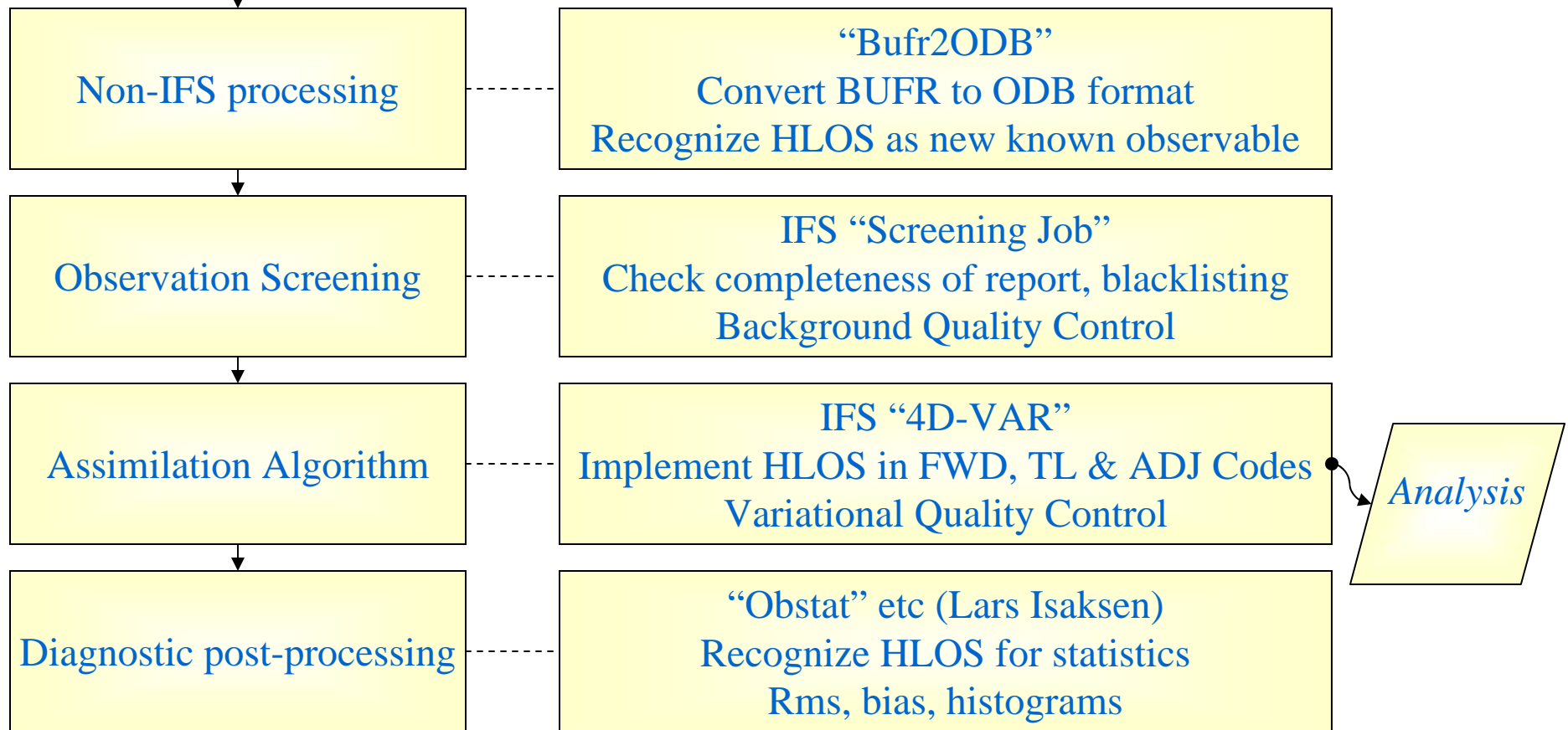
Assimilation of prototype ADM-Aeolus data

2003/4: introduced L2B hlos as new observed quantity in 4d-Var



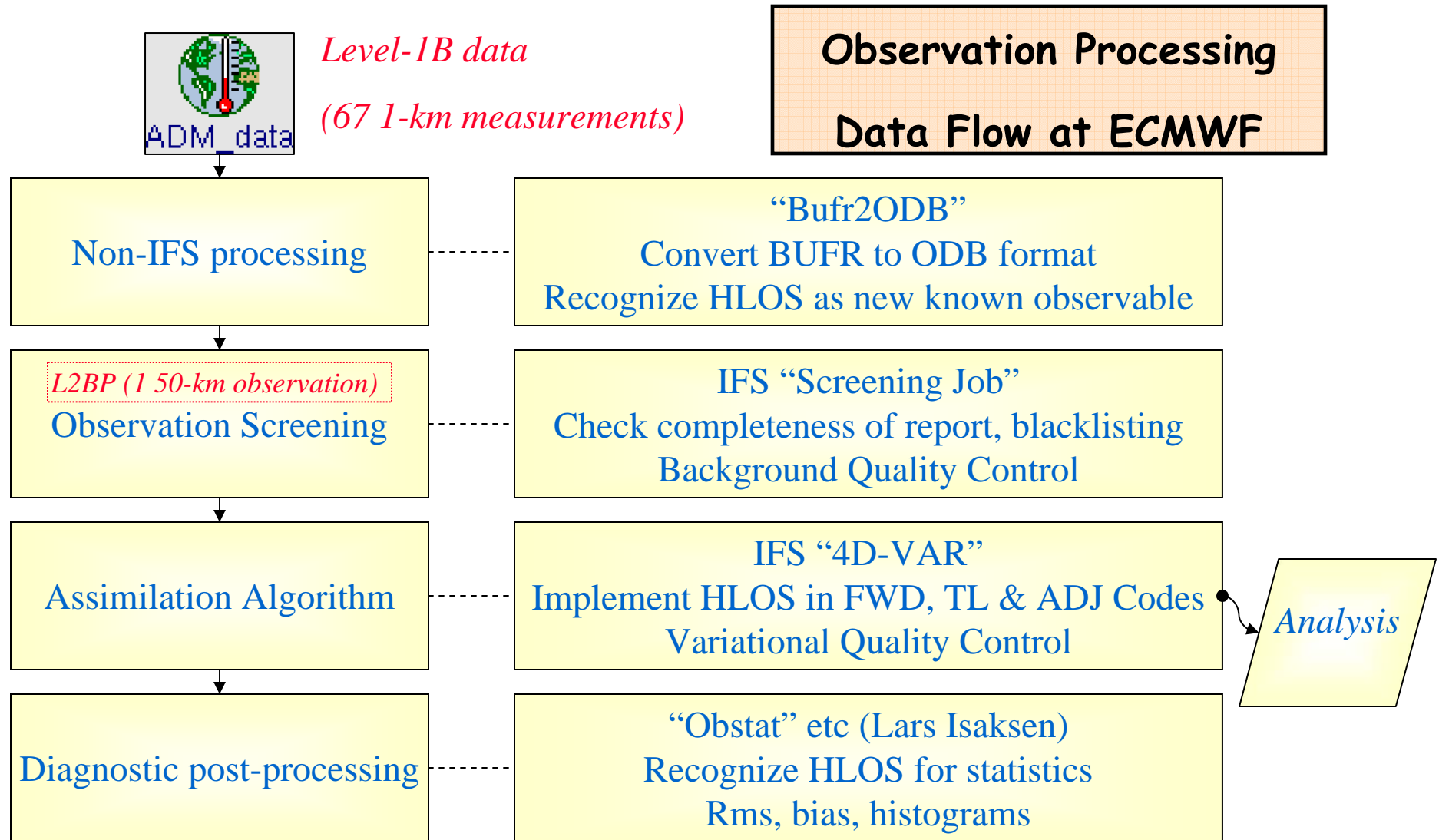
Prototype Level-2B (LIPAS simulation, includes representativeness error)

Observation Processing Data Flow at ECMWF



Assimilation of prototype ADM-Aeolus data

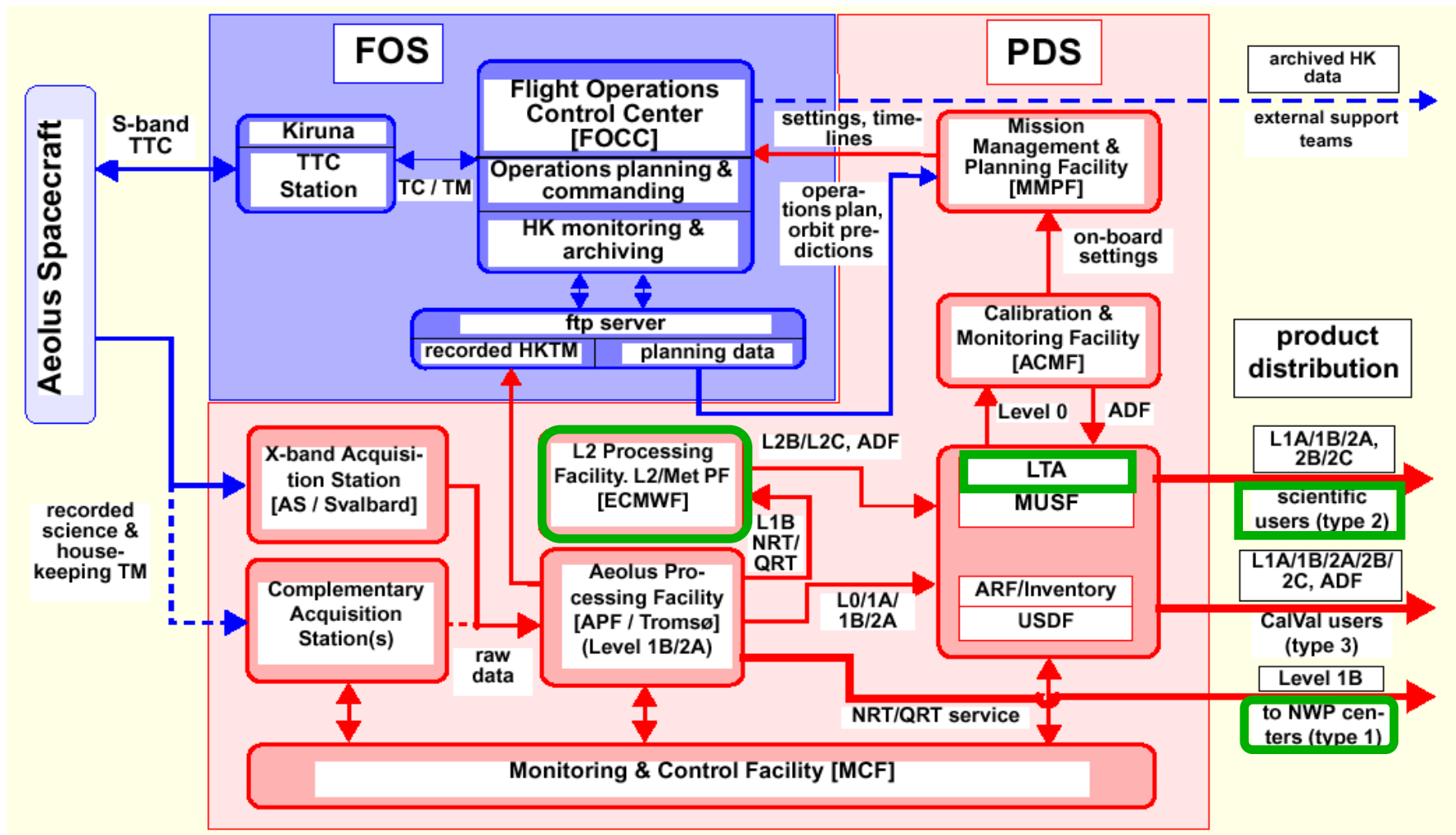
2004-: Receive L1B data & L2B processing at NWP centres



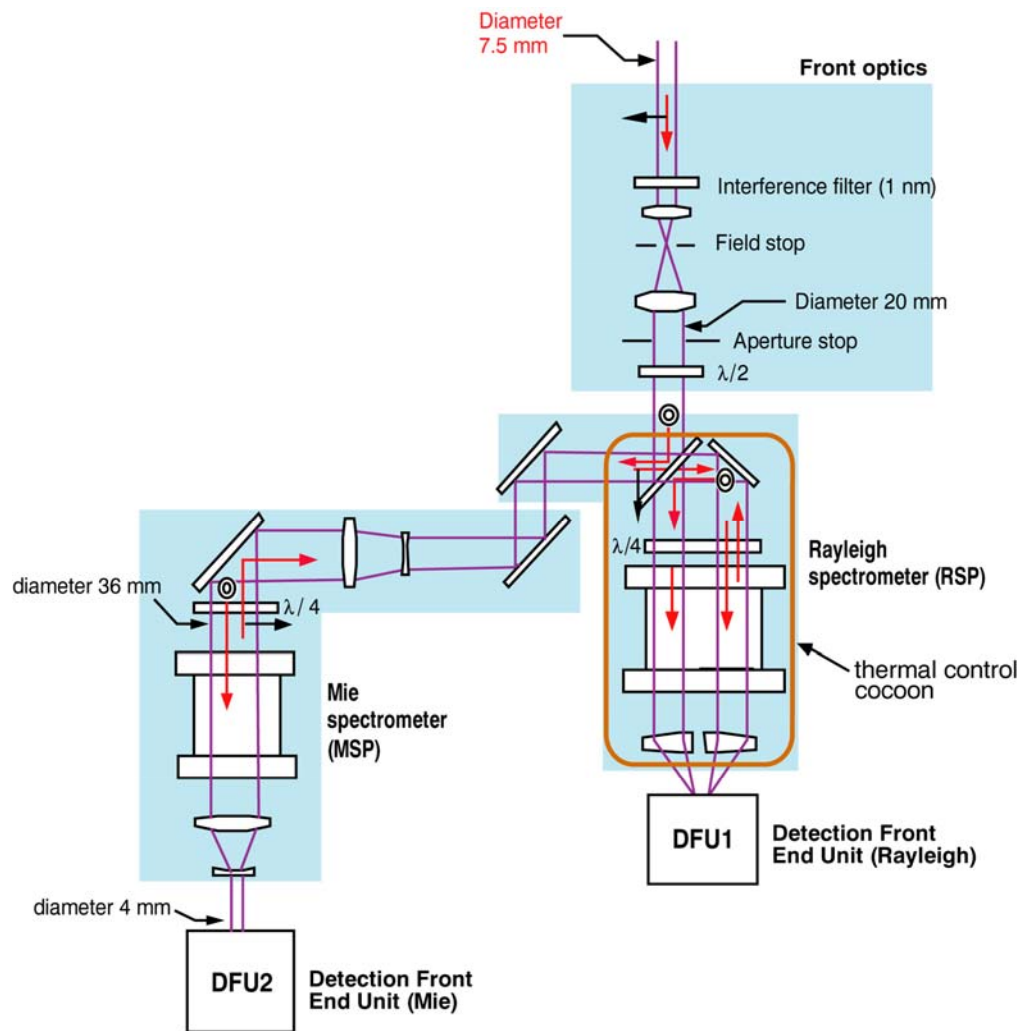
Level-2B processor will run in different environments

ECMWF will supply source code - use as standalone or callable subroutine

Aeolus Ground Segment & Data Flows - schematic view



Retrievals account for receiver properties ...

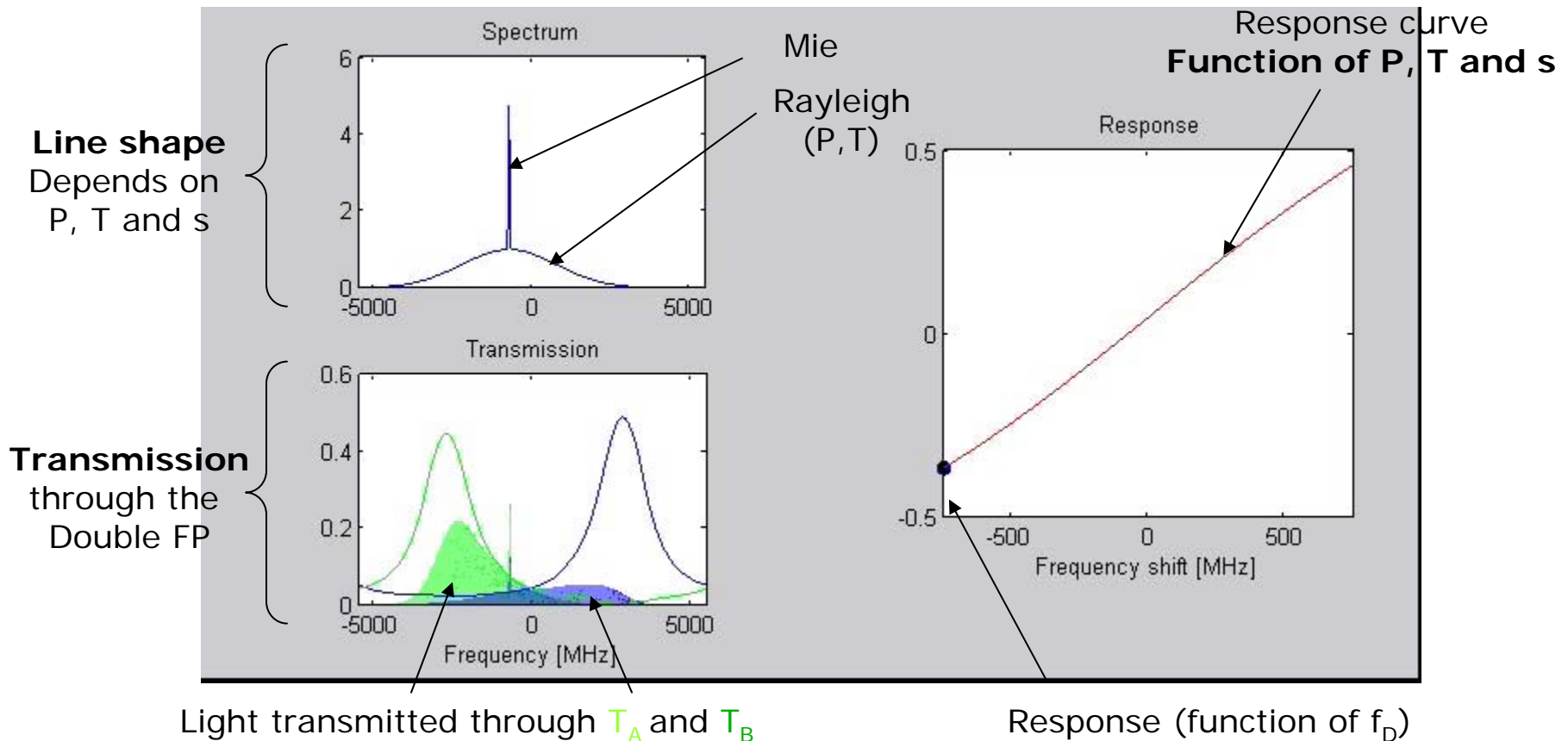


- ◆ Tan et al Tellus A 2008
- ◆ Dabas et al same issue
- ◆ Mie light reflected into Rayleigh channel
- ◆ Rayleigh wind algorithm includes correction term involving scattering ratio (s)

ADM-Aeolus Optical Receiver - Astrium Satellites

... and for atmospheric scattering properties

ILIAD – Impact of P & T and backscatter ratio on Rayleigh Responses - Dabas Meteo-France, Flamant IPSL

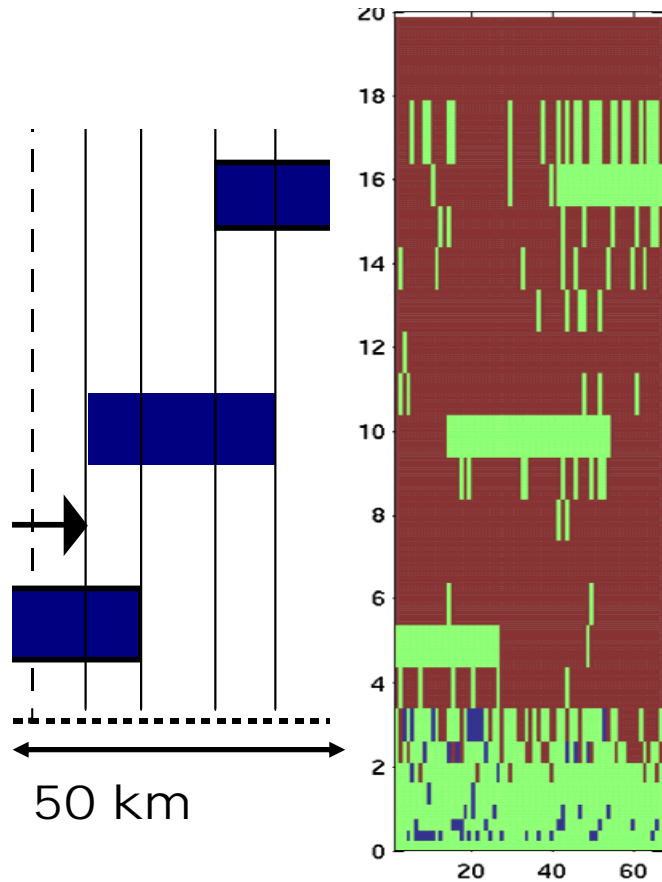


◆ **1km-scale spectra are selectively averaged**

◆ **Account for atmospheric variability - improve SNR**

Retrievals validated for idealized broken multi-layer clouds - E2S simulator + operational processing chain

Specified cloud layers	Retrieved clouds and aerosol
------------------------	------------------------------

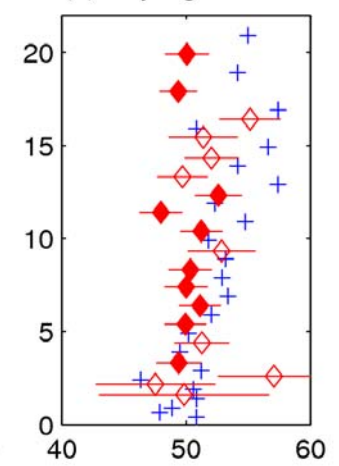


Specified wind=50 m/s

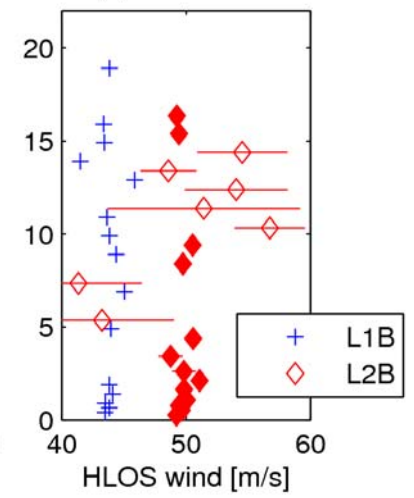
Retrieved Rayleigh winds are accurate in non-cloudy air

Retrieved Mie winds are accurate in cloud and aerosol layers

(d) Rayleigh BRC#4

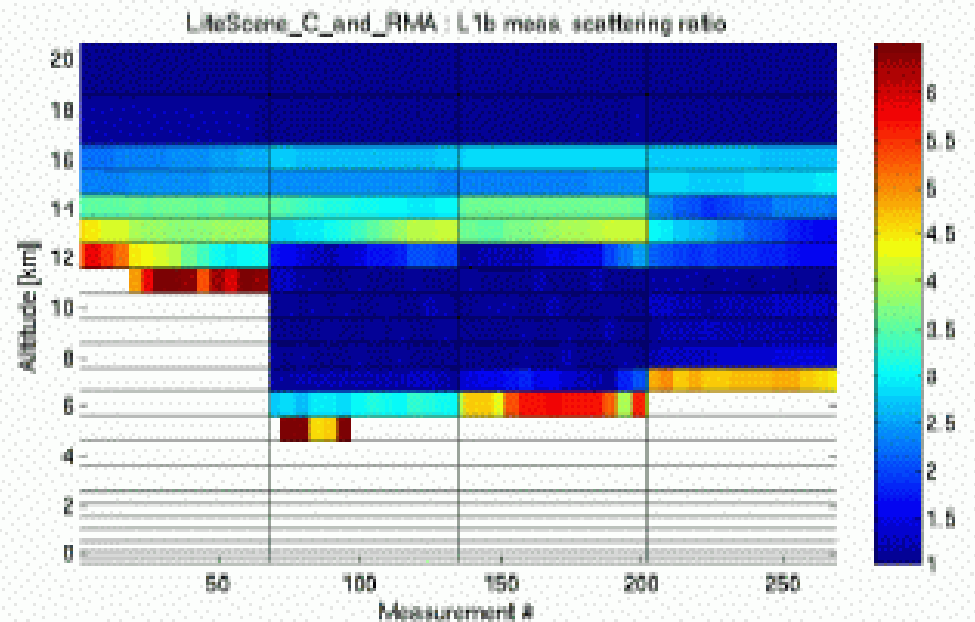
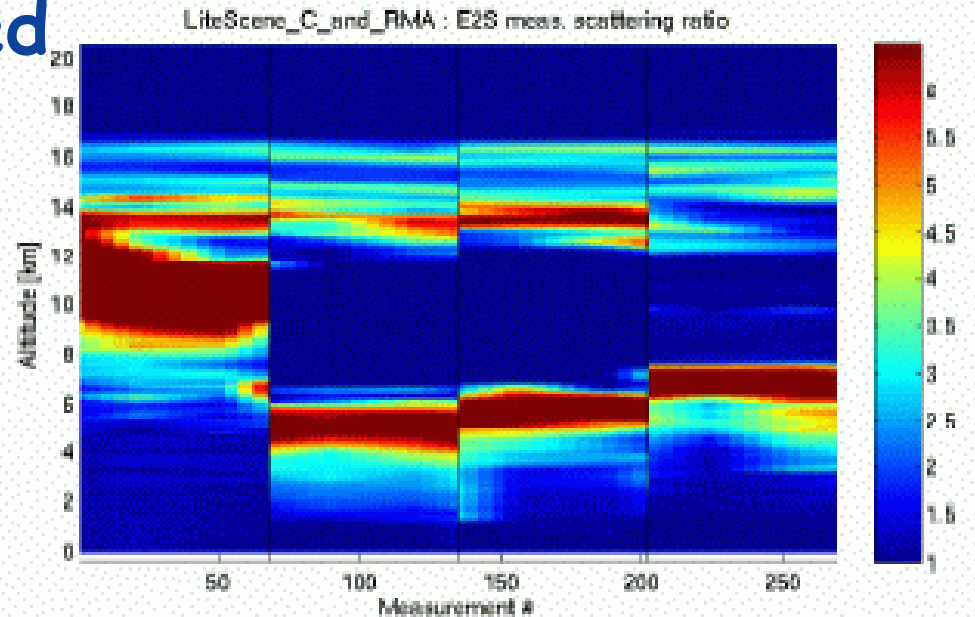


(h) Mie BRC#4



Realistic scenes simulated

- ◆ Real scattering measurements obtained from the LITE mission
ESA's software (E2S) is used to simulate what ADM-Aeolus would 'see'
- ◆ The L1B software retrieves scattering ratio at the 1 km measurement resolution
Our input not perfect

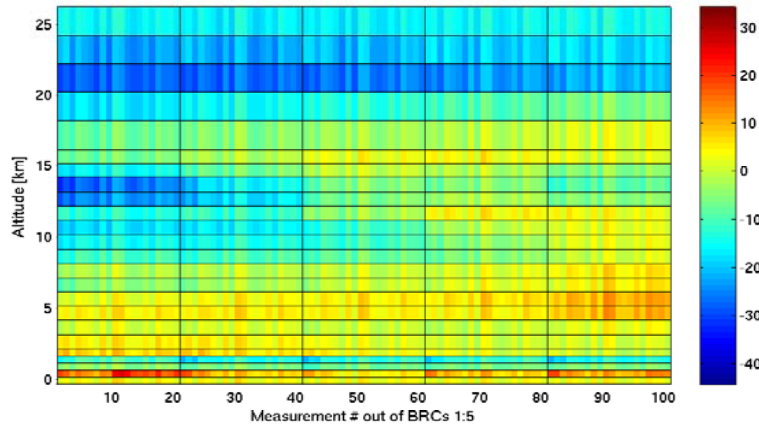


Wind retrieval validated in the presence of heterogeneous clouds and wind - E2S simulation

Rayleigh
molecular

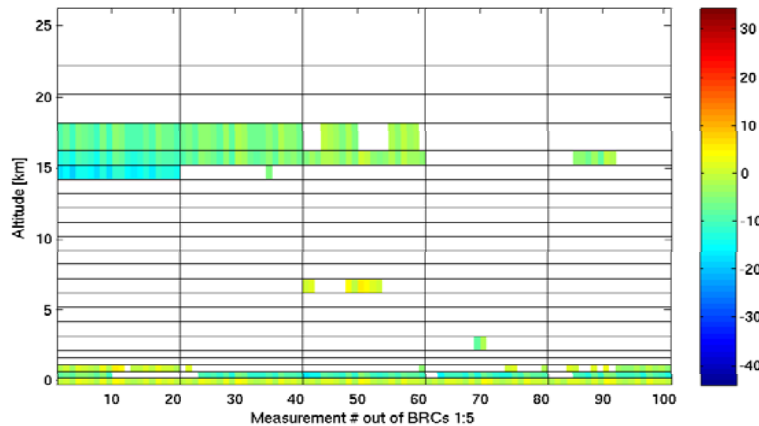
Level-1B

defaultscenario: L1b meas. wind Rayleigh

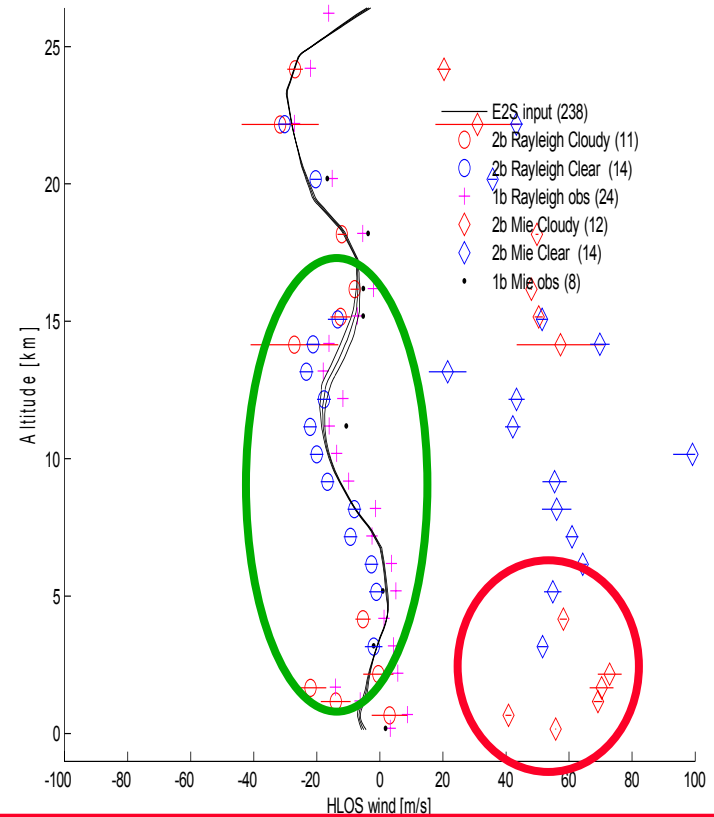


Mie
particles

defaultscenario: L1b meas. wind Mie



Retrieved Rayleigh winds are accurate - being refined

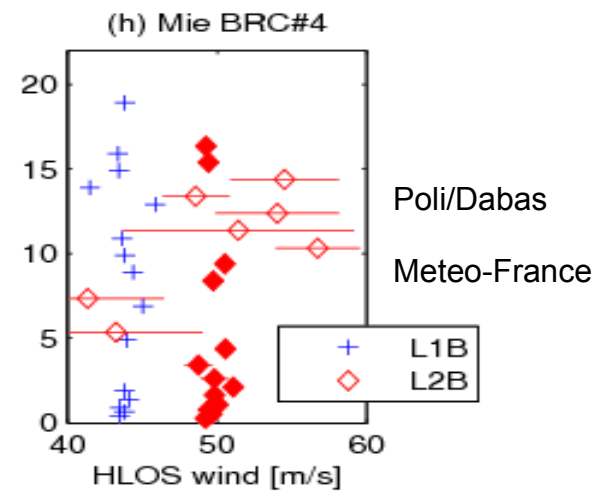
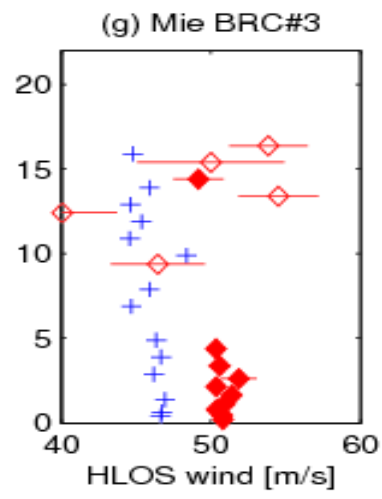
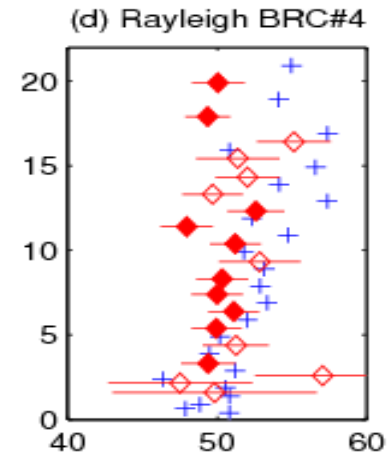
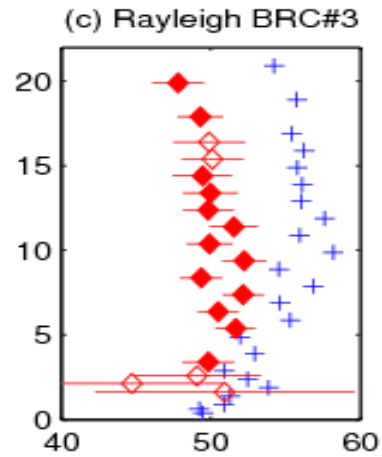
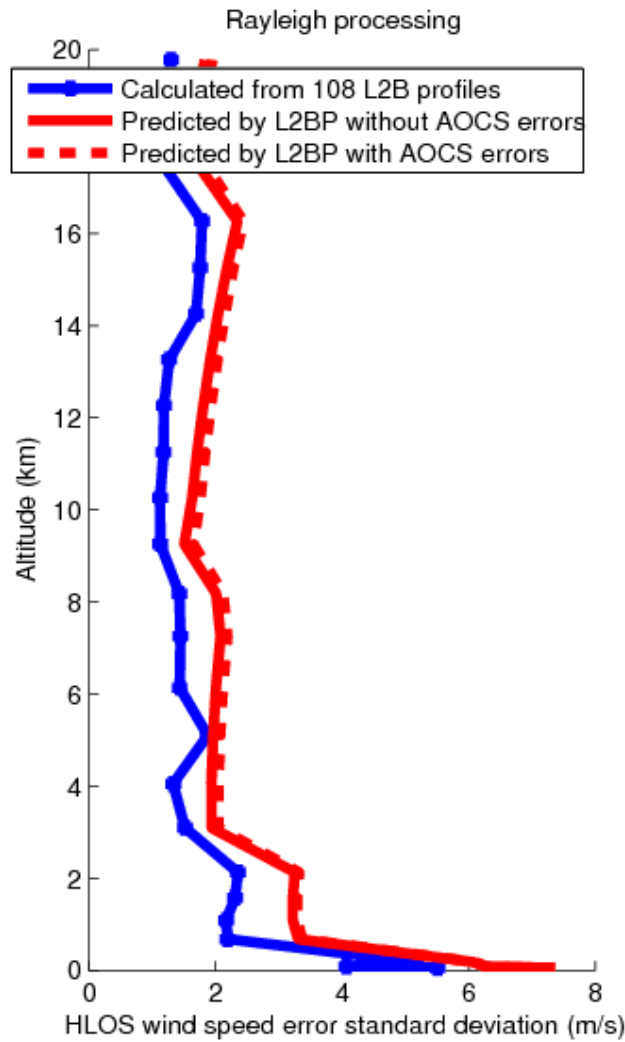


Retrieved Mie winds revealed systematic error in L1B input

Summary - Day-1 system on track

1. Level-2B hlos winds - primary product for assimilation
 - a. Account for more effects than L1B products
 - b. Will be generated in several environments
 - c. Motivated strategy to distribute source code
2. Main algorithm components developed & validated
 - a. Release 1.33 available - development/beta-testing
 - b. Documentation and Installation Tests
 - c. Portable - tested on several Linux platforms
3. Ongoing scientific and technical development
 - a. Sensitivity to inputs, QC/screening, weighting options
4. Contact points - ESA and/or ECMWF

Level-2B hlos error estimates - reqts met



Overview – why expectations are so high

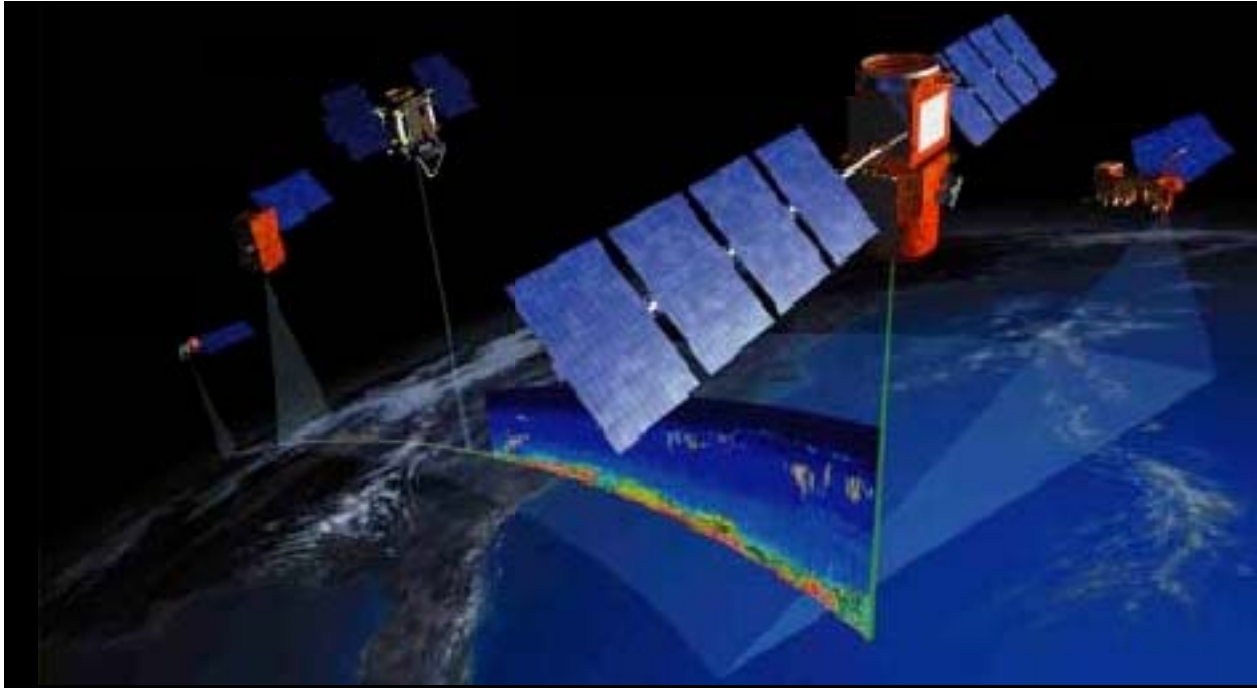
- ◆ ADM-Aeolus addresses key observational needs
 - ◆ Objectives, wind observation requirements, DWL instrument, viewing geometry
- ◆ Implementation well-advanced for launch in 2009
 - ◆ Space and ground segments
 - ◆ HLOS wind product (L2B data, algorithm, portable s-ware)
 - ◆ Cloud and aerosol products (L2A data)
 - ◆ Experimental campaigns and calibration/validation
- ◆ Studies with wind lidar data support theoretical expectations
 - ◆ Data simulations, NWP data impact studies (assimilation ensembles as alternative to OSSEs, + information content)
 - ◆ Airborne DWL (Weissman). Tropical assimilation (Zagar).

Key references

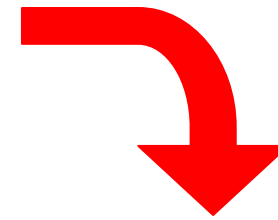
- ◆ Baker et al 1995, BAMS
- ◆ ESA 1999 Report for Assessment (Stoffelen et al 2005, BAMS) and 2007/8 Science Report
- ◆ Weissman and Cardinali 2006, QJRMS
- ◆ N. Zagar & co-authors, QJRMS & Tellus A

- ◆ Tan & Andersson 2005, QJRMS
- ◆ Tan et al 2007, QJRMS
- ◆ Tan et al 2008, Tellus A (Special Issue on ADM-Aeolus)

Background for ADM-Aeolus Measurement Concept

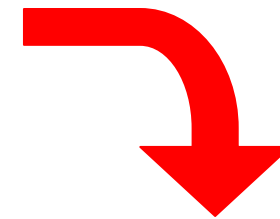
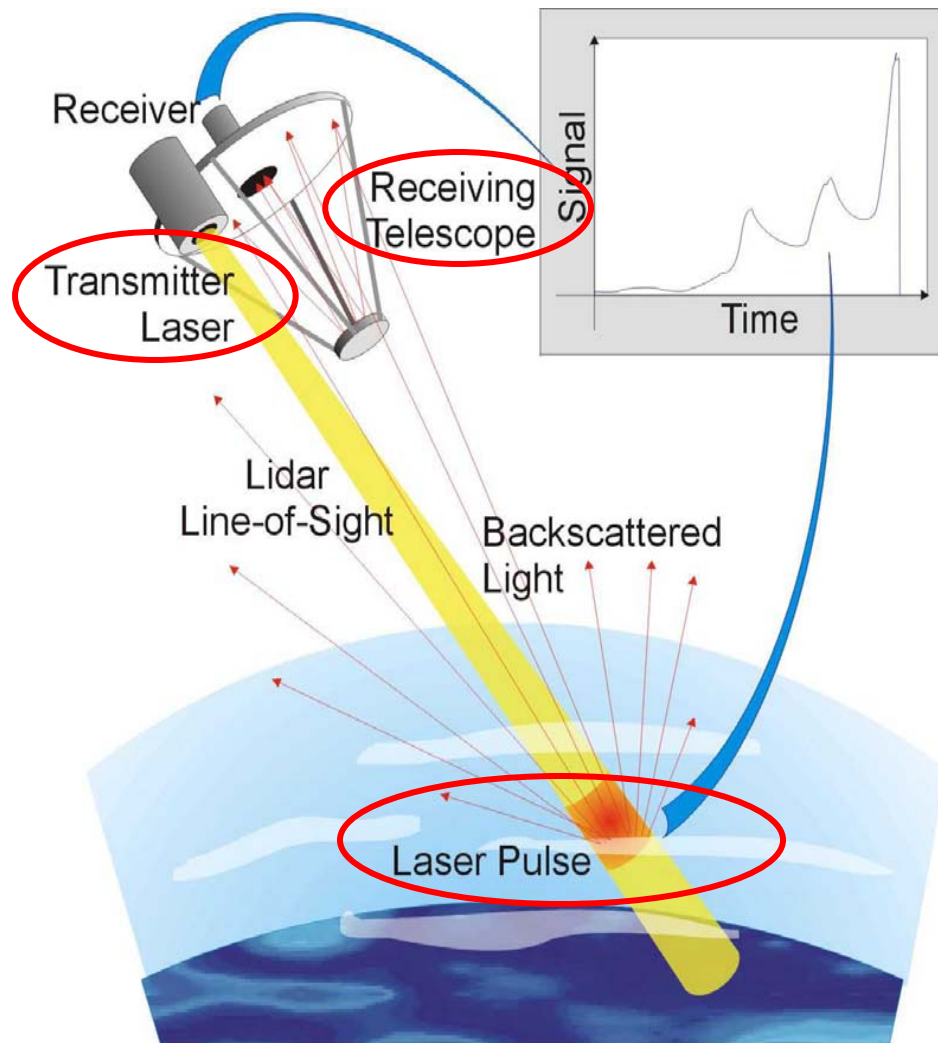


CALIPSO lidar – vertical cross sections of backscatter



- Backscatter signal
- Aeolus winds are derived from Doppler shift of aerosols **and** molecules along lidar line-of-sight
- Error estimates, cloud & aerosol properties derived from signal strength

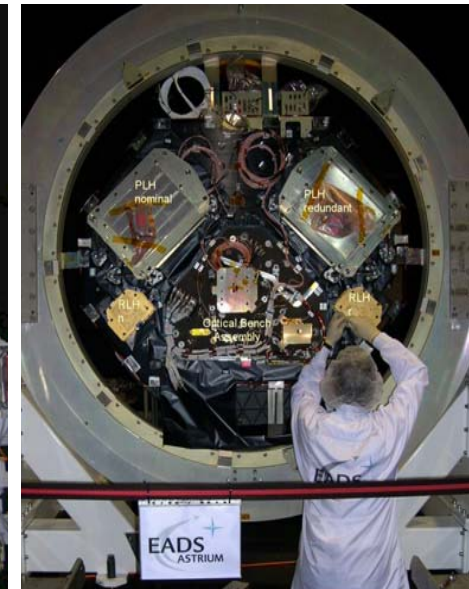
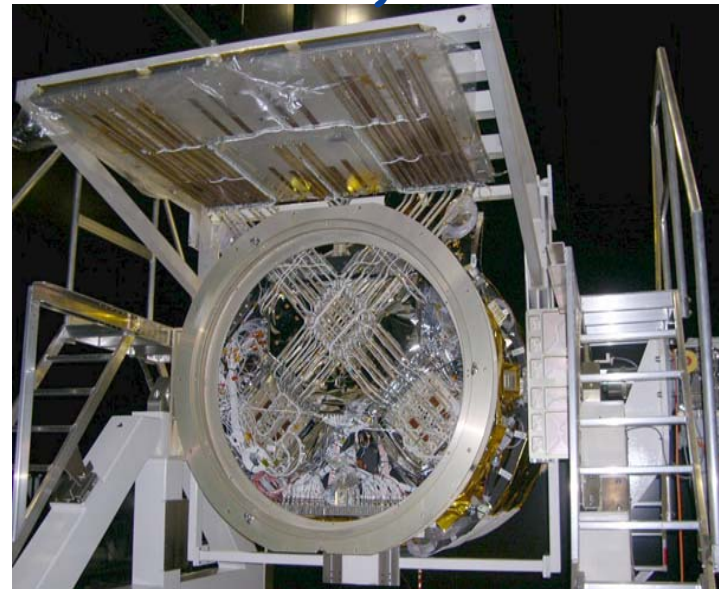
Background for ADM-Aeolus Measurement Concept



- Backscatter signal
- Winds are derived from Doppler shift of aerosols **and** molecules along lidar line-of-sight
- Error estimates, cloud & aerosol properties derived from signal strength

ADM-Aeolus Space Segment - preparation/testing of

1) structural-thermal model 2) lidar transmitter/receiver



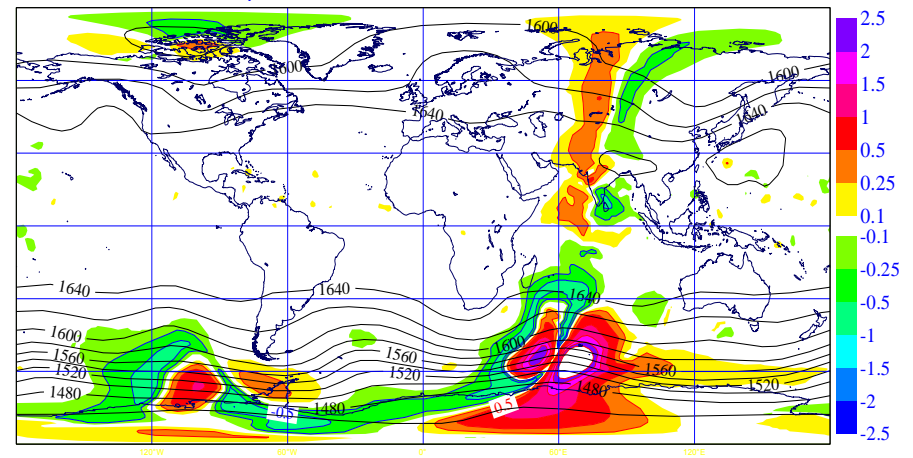
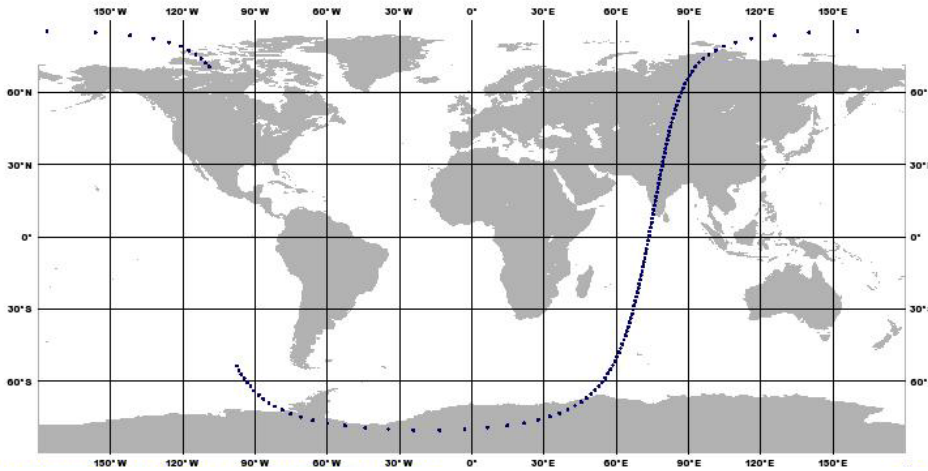
5.1 Prototype Level-2C Processing

✓ Ingestion of L1B.bufr into the assimilation system

- ◆ L1B obs locations within ODB (internal Observation DataBase)

✓ Assimilation of HLOS observations (L1B/L2B)

- ◆ Corresponding analysis increments (Z100)



5.2 Key assimilation operators

- ◆ Tan 2008 ECMWF Seminar Proceedings

- ◆ HLOS, TL and AD

- ◆ $H = -u \sin \varphi - v \cos \varphi$

- ◆ $dH = -du \sin \varphi - dv \cos \varphi$

- ◆ $dH^* = (-dy \sin \varphi, -dy \cos \varphi)^T$

- ◆ Generalize to layer averages later

- ◆ Background error

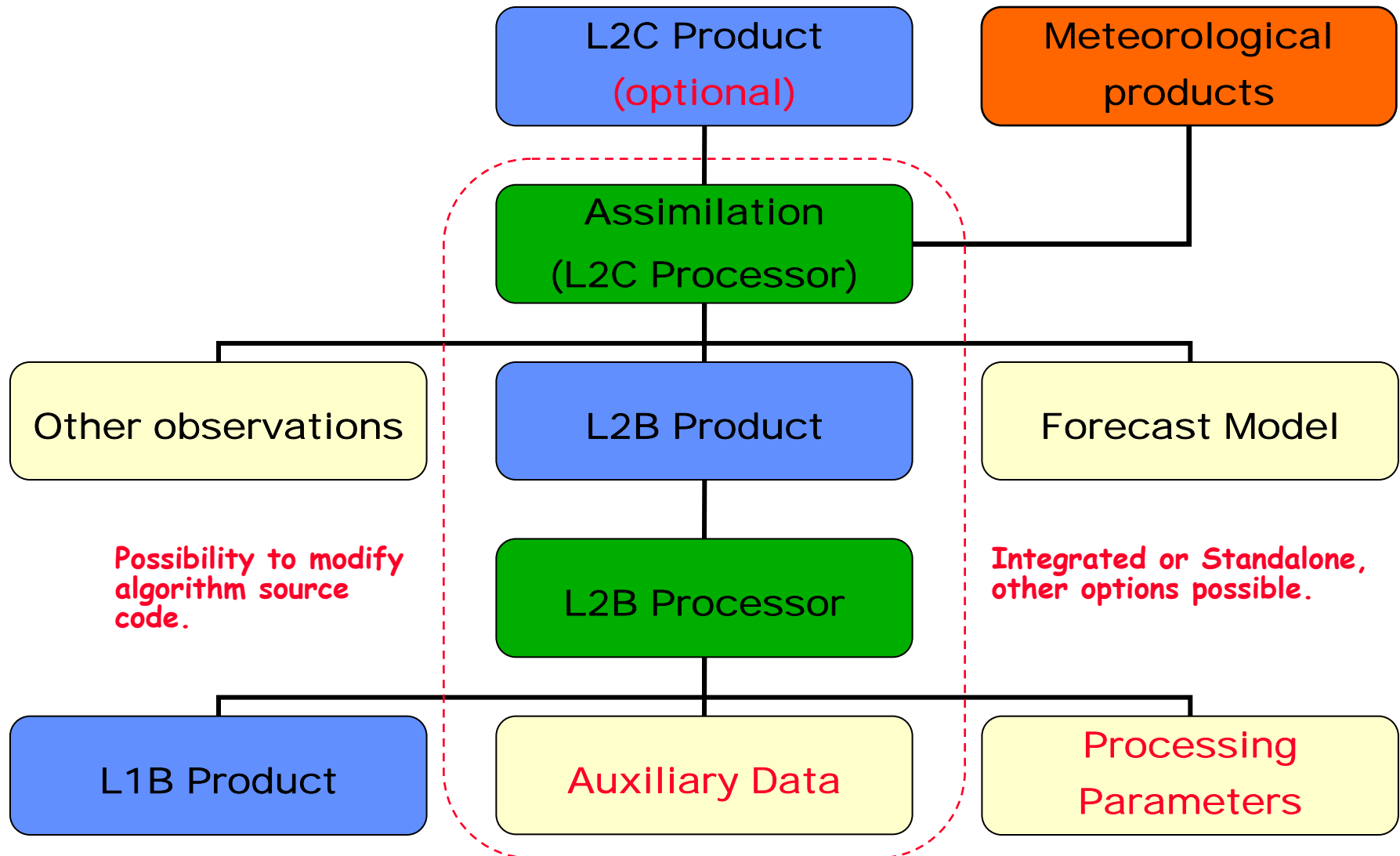
- ◆ Same as for u and v (assuming isotropy)

- ◆ Persistence and/or representativeness error

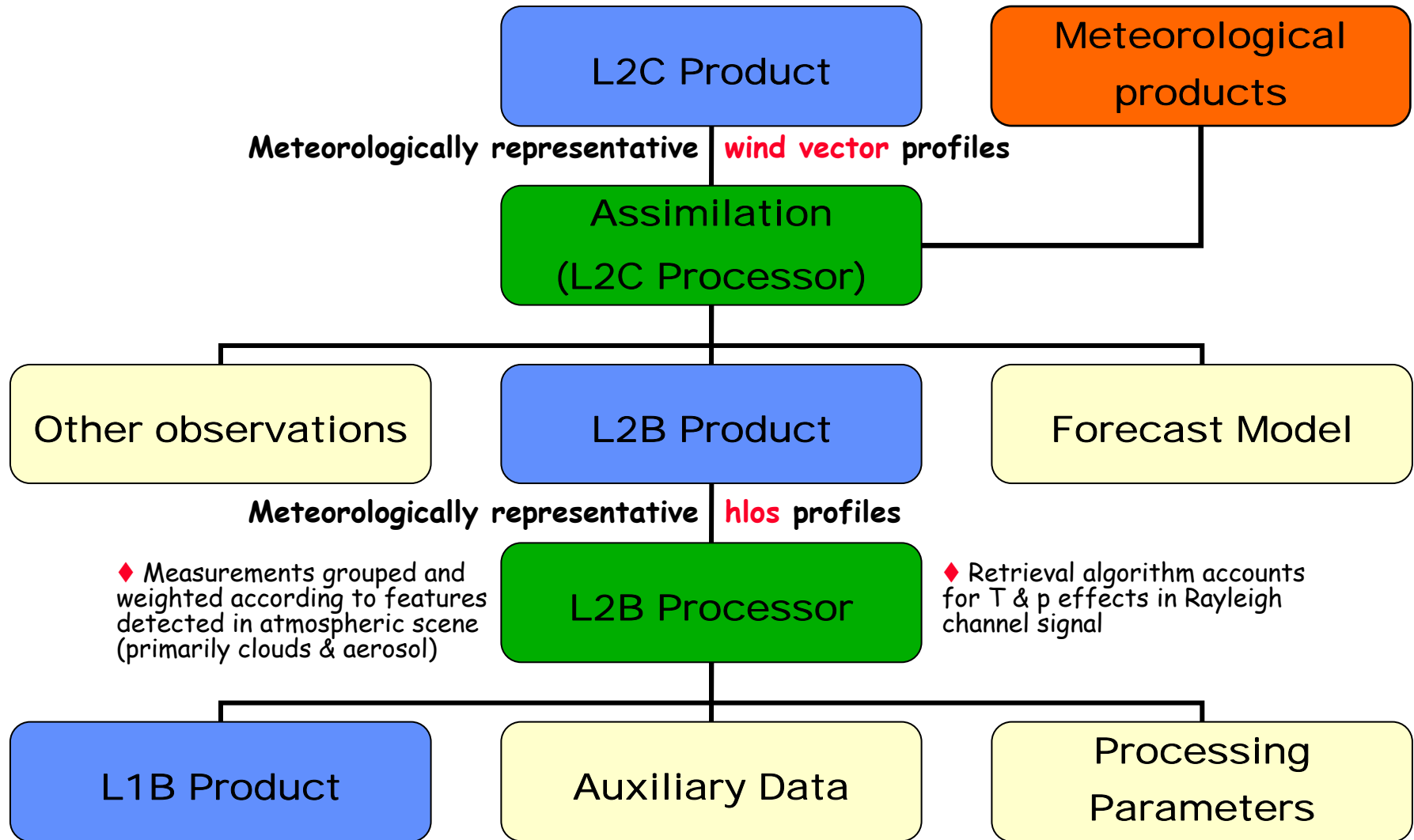
- ◆ Prototype quality control

- ◆ Adapt local practice for u and v

2a-4. Other NWP configurations



1a/b. What are Level-2B/2C Products?



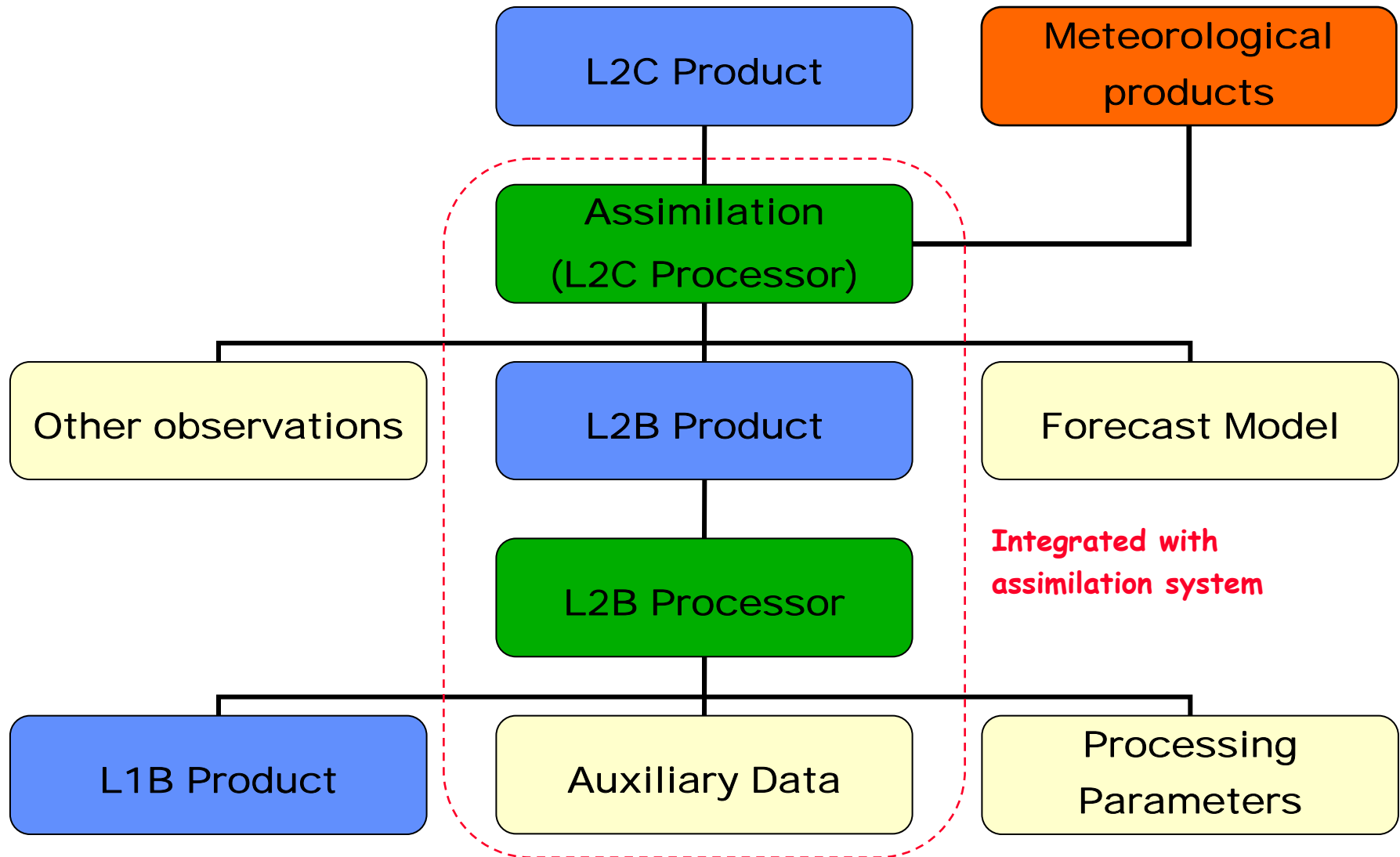
1a/b. What are Level-2B/2C Products?

- **2B: Meteorologically representative HLOS profiles**
 - retrieval algs applied to Level-1B data, 2B-output suitable as input to data assimilation
 - auxiliary input data: T & p, Rayleigh-Brillouin response data, etc
- **2C: Meteorologically representative wind vector profiles**
 - result of a data assimilation algorithm, combining Level-2B with other data/weather forecast model
- **How do they differ from Level-1B Products?**
 - Rayleigh channel retrieval accounts for T & p effects
 - measurements grouped/weighted by features detected in the atmospheric scene (primarily clouds & aerosol)

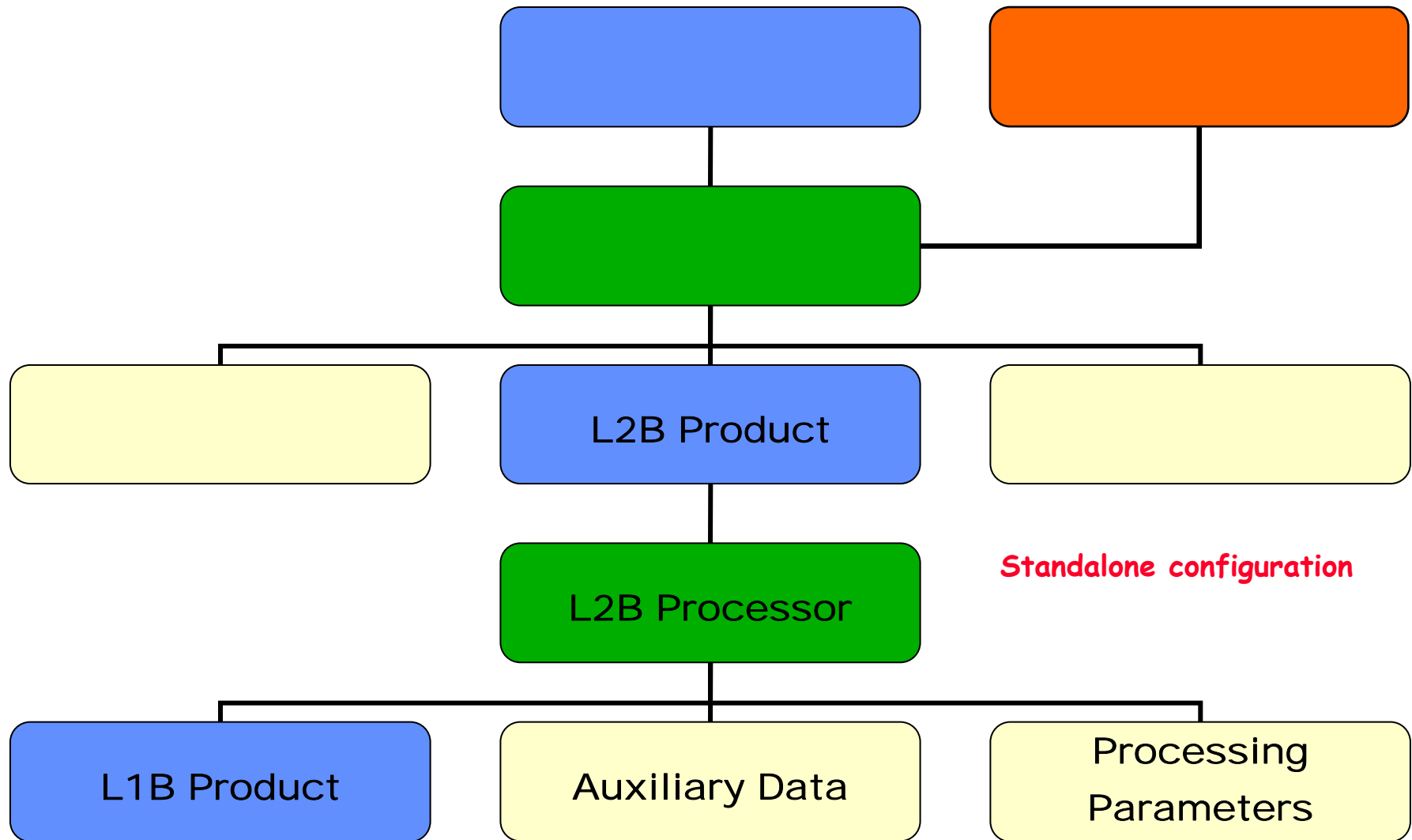
2a. Who will make Level-2B/2C Products?

- ECMWF for “operational” Level-2B/2C products
 - Processing integrated with data assimilation system
 - Products in ESA's Earth Explorer file format available from ESA (Long-Term Archive)
- ESA LTA for Level-2B late- & re-processing
 - Level-1B missing ECMWF's operational schedule
 - New processing parameters/auxiliary inputs
- Other Numerical Weather Prediction centres
 - Different operational schedule/assimilation strategy
 - Different processing params/aux inputs/algorithms
- Research institutes & general scientific users
 - Different processing params/aux inputs/algorithms

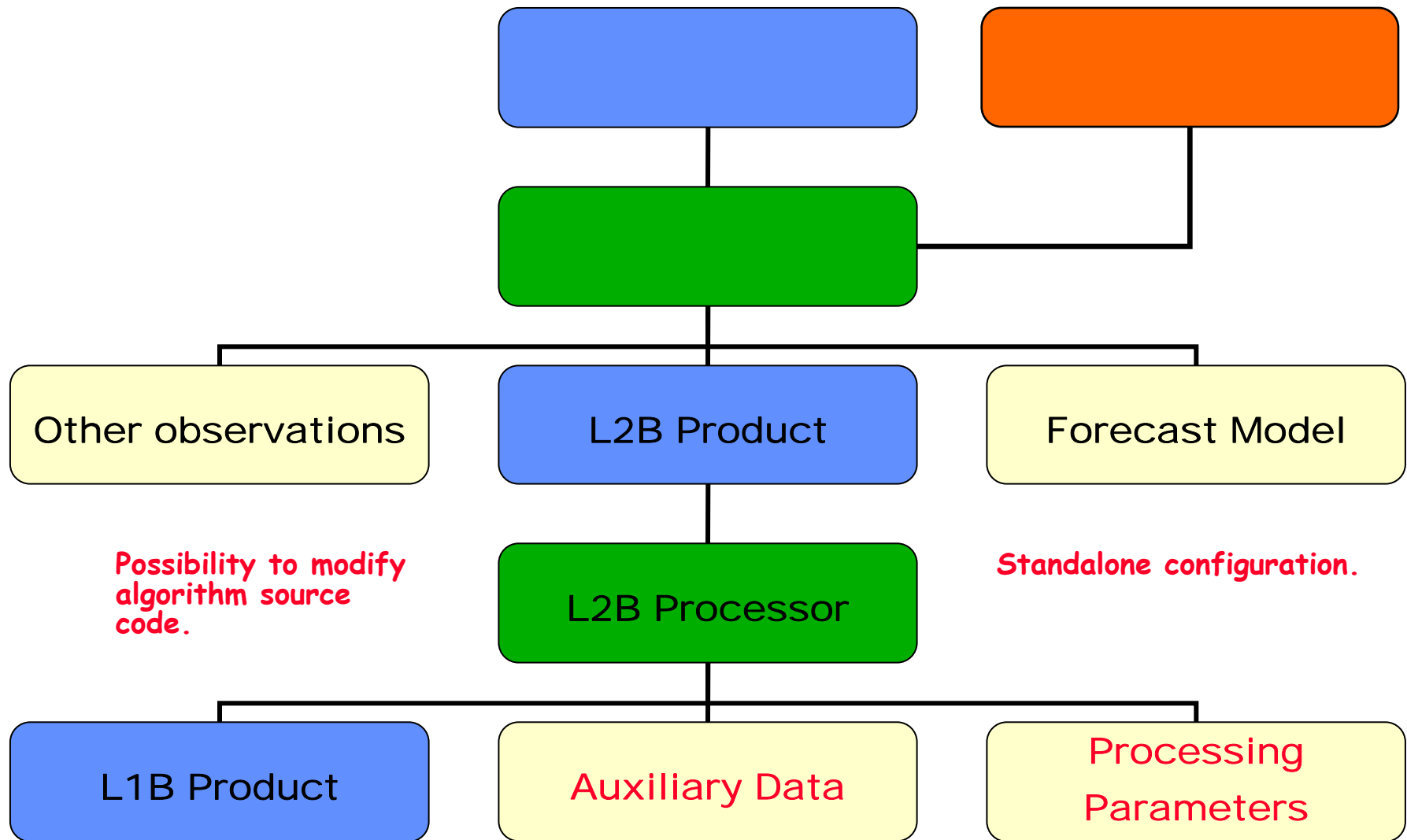
2a-1. ECMWF "operational" configuration



2a-2. ESA-LTA late- and re-processing



2a-3. Research/general scientific use



2b. Why distribute L2BP Source Code?

- **Distribution of executable binaries only permits**
 - limited number of computing platforms
 - different settings in processing parameters input file
 - thresholds for QC, cloud detection
 - different auxiliary inputs
 - option to use own meteorological data (T & p) in place of ECMWF aux met data (available from LTA)
- **Provide maximum flexibility for other centres/institutes to generate their own products**
 - different operational schedule/assimilation strategy
 - scope to improve algorithms
 - feed into new releases of the operational processor

3a. How it works - Tan et al *Tellus A* 2008

- Rayleigh channel HLOS retrieval - Dabas et al, *Tellus A*
 - $R = (A-B) / (A+B)$ and $HLOS = F^{-1}(R;T,p,s)$
 - T and p are auxiliary inputs
 - correction for Mie contamination, using estimate of scattering ratio s
- Mie channel HLOS retrieval
 - peak-finding algorithm (4-parameter fit as per L1B)
- Retrieval inputs are scene-weighted
 - $ACCD = \sum ACCD_m W_m$, W_m between 0 and 1
- Error estimate provided for every Rayleigh & Mie hlos
 - dominant contributions are SNR in each channel

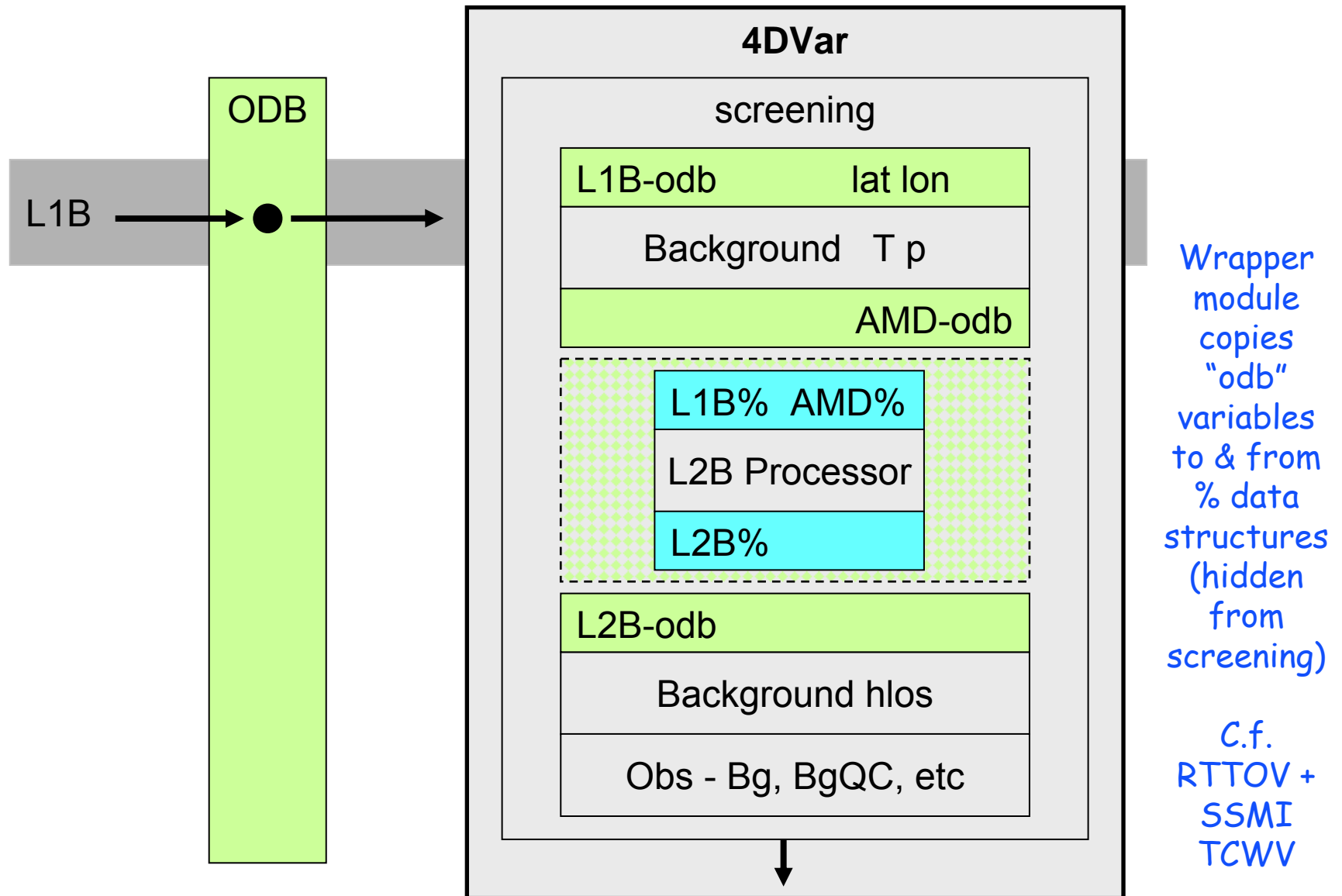
4. Distribution of L2BP software

- **Software releases issued by ECMWF/ESA**
 - Details & timings to be determined
 - Probably via registration with ECMWF and/or ESA
 - Source code and scripts for installation
 - Fortran90, some C support
 - Developed/tested under several compilers
 - Suite of unit tests with expected test output
 - Documentation
 - Software Release Note
 - Software Users' Manual
 - Definitions of file formats (IODD), ATBD, etc.

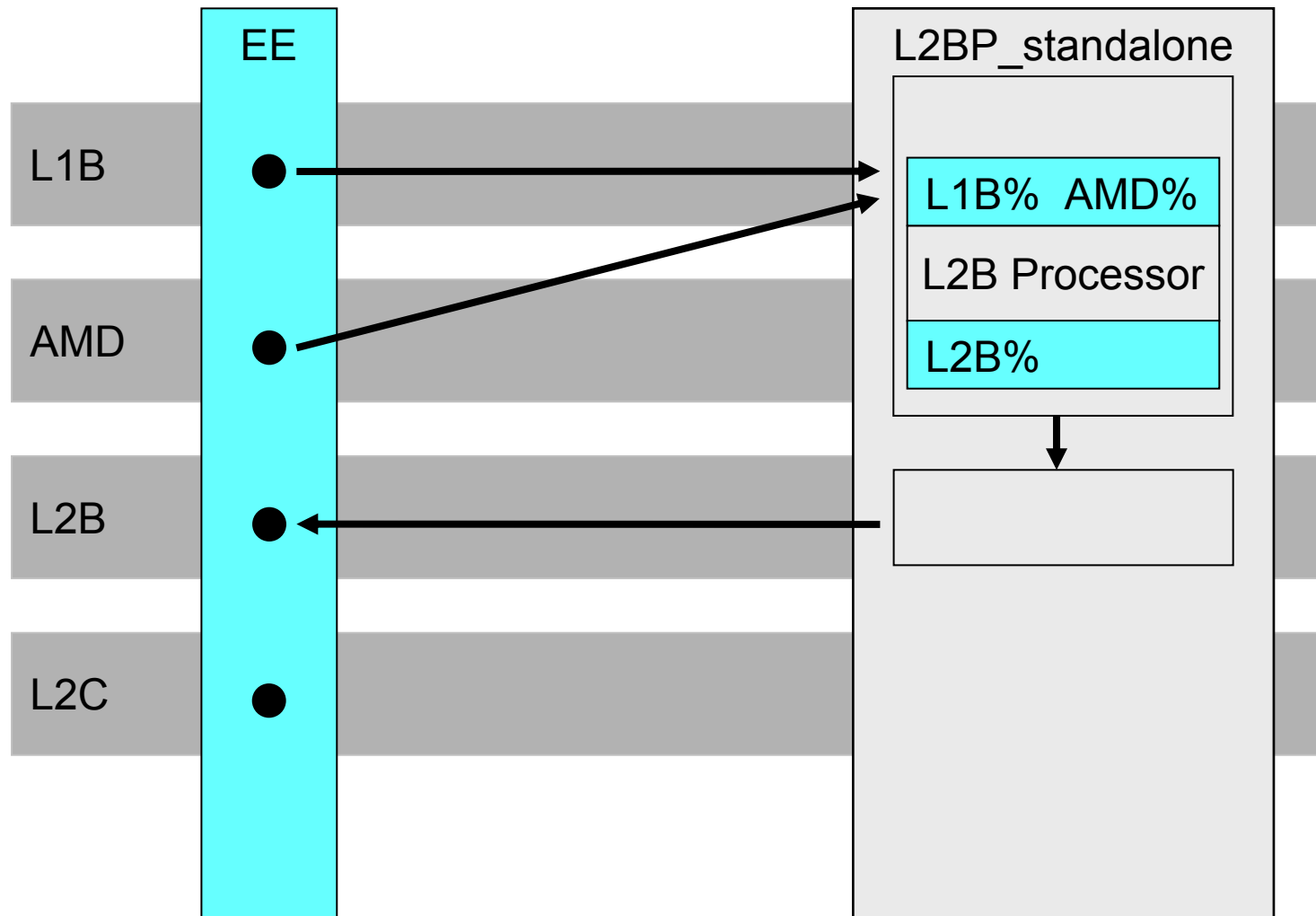
Conclusions

- **Expectations for ADM-Aeolus are high**
 - **On track for producing major benefits in NWP**
 - Meeting the mission requirements for vertical resolution & accuracy
 - Extending to stratosphere, re-analysis
 - Our software available to NWP/science community
 - **Combine with other observations**
 - Height assignment for AMVs
 - Complement other cloud/aerosol missions
 - **Related research**
 - Background error specification

5.3 L2BP integration within an assimilation system



5.4 Overview data flow - standalone mode



5.5 Principal Guidance to Met Centres

1. How to install and test the standalone version
 - ◆ Source code, documentation, unix scripts and test data (EE format) supplied
 - ◆ Useful tool for inter-comparison purposes
2. Interface requirements for integrated-assimilation mode
 - ◆ Generation of auxiliary meteorological data
 - ◆ Wrapper module between "odb" and L2B processor used as a callable subroutine within assimilation.x
 - ◆ Both to occur during Screening
 - ◆ Facilitates assimilation of Aeolus data
 - ◆ Assimilation outputs at discretion of each met centre